## Generalized symmetries as homotopy Lie algebras

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# What do we know about physics at quantum gravity scales?

- Appropriate space-time probe is not a point particle.
- Concept of symmetry needs to be generalized.
- Field content needs to be extended.
- \* Wilsonian separation of scales (probably) fails in QG regime.

Different aspects made precise in string theory, holography, matrix/tensor models....

# What are the relevant symmetries at quantum gravity scales?

In string theory space-time probe is spatially extended, eg strings and branes

- → couple to higher gauge potential → higher gauge theories
- → low-energy effective dynamics → non-commutative/non-associative deformation

## What are the relevant symmetries at quantum gravity scales?

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- → couple to higher gauge potential → higher gauge theories
- → low-energy effective dynamics → non-commutative/non-associative deformation

 $\rightarrow$  natural framework for the description of generalized symmetries in the quantum gravity regime  $\rightarrow$  homotopy Lie algebras ( $L_{\infty}$ -algebras), Stasheff '63, Stasheff, Schlesinger '77

#### In this talk

#### GOAL

Demonstrate that  $L_{\infty}$ -algebra is natural framework for the description of generalized symmetries.

#### PLAN

- ullet  $L_{\infty}$ -algebra short introduction
- ullet  $L_{\infty}$ -algebra coalgebra formulation
- Drinfel'd twist of  $L_{\infty}$ -algebra
- DFT algebroid

 $L_{\infty}$ -algebra

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- Quantization
  - ▶ BV formalism  $\sim L_{\infty}$ -algebra Zwiebach '92
  - ightharpoonup Deformation quantization: formality thm  $\sim L_{\infty}$  quasi-isomorphism Kontsevich '97; Poisson sigma model quantization Cattaneo, Felder, '99

 $L_{\infty}$ -algebra  $\leadsto$ generalization of differential graded Lie algebras encoding both the kinematics and dynamics of a given field theory.

- Geometry
  - ▶ Graded geometry:  $L_{\infty}$ -algebra (cyclic)  $\equiv$  Q(P) manifolds AKSZ '95
  - ► Generalized geometry of Courant, double field theory and exceptional algebroids Roytenberg, Weinstein '98; Deser, Saemann '16, LJ, Grewcoe '20; Cederwall, Palmkvist '18

 $L_{\infty}$ -algebra  $\leadsto$  generalizations of differential graded Lie algebras.

- Quantization → BV-BRST, deformation quantization
- Graded and generalized geometry
- NC/NA field theory and gravity
  - ► \*-product: bootstraping nc gauge theories using L<sub>∞</sub> Blumenhagen et al '18
  - ▶ Drinfel'd twist and braided L<sub>∞</sub> Dimitrijević Ćirić et al '21, Nguyen, Schenkel, Szabo '21
  - ► HS in unfolded formalism Vasiliev

#### Algebra formulation

Def1: An  $L_{\infty}$ -algebra  $(L, \mu_i)$  is a  $\mathbb{Z}$ -graded vector space  $L = \bigoplus_k L_k$  with a collection of graded totally antisymmetric multilinear maps

$$\mu_i: \underbrace{\mathsf{L} \times \cdots \times \mathsf{L}}_{i\text{-times}} \to \mathsf{L}.$$

of degree 2 - i which satisfy the homotopy Jacobi identities:

$$\sum_{i+k-n} \sum_{\sigma} \chi(\sigma; l_1, \dots, l_n) (-1)^k \mu_{k+1}(\mu_j(l_{\sigma(1)}, \dots, l_{\sigma(j)}), l_{\sigma(j+1)}, \dots, l_{\sigma(n)}) = 0;$$

$$\forall n \in \mathbb{N}_0 \quad \forall I_i \in L.$$

 $\chi(\sigma; l_1, \ldots, l_n)$  is the graded Koszul sign that includes the sign from the parity of the permutation  $\sigma$  ordered as:  $\sigma(1) < \cdots < \sigma(j)$  and  $\sigma(j+1) < \cdots < \sigma(n)$ .

n = 0:  $\mu_1 \mu_0 = 0$ 

$$\begin{split} n &= 1 \colon \ \mu_1^2(I) = \mu_2(\mu_0, I) \\ n &= 2 \colon \ \mu_1(\mu_2(h, h_2)) - \mu_2(\mu_1(h_1), h_2) - (-1)^{1+|h_1||h_2|} \mu_2(\mu_1(h_2), h_1) = -\mu_3(\mu_0, h_1, h_2) \\ \\ n &= 3 \colon \ \mu_1(\mu_3(h_1, h_2, h_3)) - \mu_2(\mu_2(h_1, h_2), h_3) - (-1)^{|h_2||h_3|} \mu_2(\mu_2(h_1, h_3), h_2) - \\ &\quad - (-1)^{|h_1|(h_2|+|h_3|)} \mu_2(\mu_2(h_2, h_3), h_1) + \mu_3(\mu_1(h_1), h_2, h_3) - \\ &\quad - (-1)^{|h_1||h_2|} \mu_3(\mu_1(h_2), h_1, h_3) + (-1)^{|h_3|(|h_1|+|h_2|)} \mu_3(\mu_1(h_3), h_1, h_2) = \mu_4(\mu_0, h_1, h_2, h_3), \end{split}$$

$$n = 1: \ \mu_1^2(I) = \mu_2(\mu_0, I)$$

$$n = 2: \ \mu_1(\mu_2(h_1, h_2)) - \mu_2(\mu_1(h_1), h_2) - (-1)^{1+|h_1||h_2|} \mu_2(\mu_1(h_2), h_1) = -\mu_3(\mu_0, h_1, h_2)$$

$$\begin{split} n &= 3: \; \mu_1(\mu_3(I_1,I_2,I_3)) - \mu_2(\mu_2(I_1,I_2),I_3) - (-1)^{|I_2||I_3|} \mu_2(\mu_2(I_1,I_3),I_2) - \\ &- (-1)^{|I_1|(|I_2|+|I_3|)} \mu_2(\mu_2(I_2,I_3),I_1) + \mu_3(\mu_1(I_1),I_2,I_3) - \\ &- (-1)^{|I_1||I_2|} \mu_3(\mu_1(I_2),I_1,I_3) + (-1)^{|I_3|(|I_1|+|I_2|)} \mu_3(\mu_1(I_3),I_1,I_2) = \mu_4(\mu_0,I_1,I_2,I_3), \end{split}$$

Given  $(\mu_0)$ ,  $\mu_1$ ,  $\mu_2$  the rest can be "bootstrapped".

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 $n=3: \rightsquigarrow$  generalized Jacobi identity for bracket  $\mu_2$  controlled by higher brackets

When  $\mu_0 = 0$ ,  $\mu_1$  is differential on L and a derivation of (super)bracket  $\mu_2$ . The elements of graded vector space  $L = \bigoplus_k L_k$  form a cochain complex

$$\cdots \xrightarrow{\mu_1} \mathsf{L}_k \xrightarrow{\mu_1} \mathsf{L}_{k+1} \xrightarrow{\mu_1} \cdots$$

Ex1:  $\mu_i = 0$  for  $i \neq 2 \rightsquigarrow$  graded Lie algebra with  $\mu_2$  being graded Lie bracket.

Ex2:  $\mu_i = 0$  for  $i \ge 3 \leadsto$  curved differential graded Lie algebra.

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Cdgla: Graded Lie algebra  $\mathfrak{g}$ , derivation d with degree 1, and curvature R of degree 2 s.t.

$$dR = 0$$
,  $d^2x = [R, x], \forall x \in \mathfrak{g}$ .

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 $L_{\infty}$ : Graded vector space L with maps  $R \leadsto \mu_0$ ,  $d \leadsto \mu_1$ , the graded Lie bracket  $\leadsto \mu_2$ , satisfying the homotopy relations

$$\mu_1\mu_0=0$$
,  $\mu_1(\mu_1(I))=\mu_2(\mu_0,I), I\in L$ .

Leibniz: 
$$\mu_1(\mu_2(l_1, l_2)) = \mu_2(\mu_1(l_1), l_2) + (-1)^{1+|l_1||l_2|} \mu_2(\mu_1(l_2), l_1)$$

$$\mathsf{Jacobi:}\ \mu_2(\mu_2(\mathit{I}_1,\mathit{I}_2),\mathit{I}_3) + (-1)^{|\mathit{I}_2||\mathit{I}_3|}\mu_2(\mu_2(\mathit{I}_1,\mathit{I}_3),\mathit{I}_2) + (-1)^{|\mathit{I}_1|(|\mathit{I}_2|+|\mathit{I}_3|)}\mu_2(\mu_2(\mathit{I}_2,\mathit{I}_3),\mathit{I}_1) = 0$$

 $\underline{\text{Maurer-Cartan (MC) elements}}$  of  $L_{\infty}\text{-algebra}$  are elements of homogeneous subspace  $L_1$  satisfying

$$\mu_0 + \mu_1(x) + \frac{1}{2!}\mu_2(x,x) + \frac{1}{3!}\mu_3(x,x,x) + \dots = 0, x \in L_1$$

 $generalised \ MC \ equation.$ 

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generalised MC equation.

 $\underline{L_{\infty}\text{-morphism}} \text{ between two } L_{\infty}\text{-algebras } (\mathsf{L},\mu) \text{ and } (\mathsf{L}',\mu') \text{ is a collection of multilinear,} \\ \text{totally graded antisymmetric homogeneous maps } \phi_i:\mathsf{L}^{\times i}\to\mathsf{L}' \text{ of degree } 1-i,\ i\in\mathbb{N}_0 \text{ if...}$ 

$$\begin{split} \phi_1(\mu_1(I)) &= \mu_1'(\phi_1(I)) \\ \phi_1(\mu_2(I_1, I_2)) &- \phi_2(\mu_1(I_1), I_2) + (-1)^{|I_1||I_2|} \phi_2(\mu_1(I_2), I_1) = \mu_1'(\phi_2(I_1, I_2)) + \mu_2'(\phi_1(I_1), \phi_1(I_2)) \end{split}$$

...

#### $L_{\infty}$ - perturbative field theory - sketch

Hohm, Zwiebach '17; Jurčo et al. '18, '20; Giotopoulos, Szabo '21

- $L_{\infty} \rightsquigarrow$  symmetry (gauge) algebra
- MC equations → eoms

$$\sum_{i} \frac{1}{i!} \mu_i(x,\ldots,x) = 0 \ , x \in L_1$$

$$\delta_c x = \sum_i \frac{1}{i!} \mu_{i+1}(x,\ldots,x,c) , c \in L_0$$

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To define a classical action and/or solution of classical master equation we need:

- Tensor product (of complexes)
- Inner product → cyclic L<sub>∞</sub>

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- Tensor product (of complexes)
- Inner product  $\rightsquigarrow$  cyclic  $L_{\infty}$

$$S_{\mathrm{MC}}[x] \equiv \sum_{i \geq 0} \frac{1}{(i+1)!} \langle x, \mu_i(x, \dots, x) \rangle.$$

#### $L_{\infty}$ - perturbative field theory - sketch

Hohm, Zwiebach '17; Jurčo et al. '18, '20; Giotopoulos, Szabo '21

- quasi-isomorphisms → equivalent field theories
- homotopy transfer → effective field theories
- minimal model thm → tree level amplitudes
- quantum homotopy → loops c.f. Brano talk
- renormalization Costello; Chiaffrino, Sachs '21, c.f. Kasia talk

Lada, Stasheff '92, Lada, Markl '94

An  $L_{\infty}$  algebra is a  $\mathbb{Z}$ -graded vector space

$$X = \bigoplus_{d \in \mathbb{Z}} X_d$$

with multilinear graded symmetric maps  $b_i: X^{\otimes i} \to X$  of degree 1 such that the coderivation  $D = \sum_{i=0} b_i$  is nilpotent.

$$\begin{split} D^2 &= 0 : b_1(b_0) = 0 \ , \\ b_2(b_0,x) + b_1^2(x) &= 0 \ , \\ b_3(b_0,x_1,x_2) + b_2(b_1(x_1),x_2) + (-1)^{|x_1||x_2|} b_2(b_1(x_2),x_1) + b_1(b_2(x_1,x_2)) &= 0 \ . \end{split}$$

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Suspension or shift isomorphism s

$$s: L \to L[1]$$
 s.t.  $(L[1])_d = X_{d+1}$ ,

induces isomorphism of graded algebras and décalage isomorphism of brackets

$$\mu_i = (-1)^{\frac{1}{2}i(i-1)+1}s^{-1} \circ b_i \circ s^{\otimes i}$$
.

Extend the maps  $b_i$  on the whole graded symmetric tensor algebra over field  $K=:S^0X$ 

$$S(X) := \bigoplus_{n=0}^{\infty} S^n X ,$$

with graded symmetric tensor product  $\vee$ .

The maps  $b_i: S^j X \to S^{j-i+1} X$  act as a coderivation:

where  $\epsilon(\sigma; x)$  is the Koszul sign, and  $\operatorname{Sh}(p, m - p) \in S_m$  denotes those permutations ordered as  $\sigma(1) < \cdots < \sigma(p)$  and  $\sigma(p+1) < \cdots < \sigma(m)$ .

Introducing the permutation map  $au^{\sigma}: X^{\otimes i} \to X^{\otimes i}$ 

$$b_i \circ \mathrm{id}^{\vee j} = \sum_{\sigma \in \mathrm{Sh}(i,j-i)} (b_i \vee \mathrm{id}^{\vee (j-i)}) \circ \tau^{\sigma} , \qquad j \geq i .$$

Degree 1 coderivation  $D: S(X) \rightarrow S(X)$  satisfies the co-Leibniz property:

$$\Delta \circ D = (1 \otimes D + D \otimes 1) \circ \Delta ,$$

with the coproduct map map  $\Delta: \mathsf{S}(X) \to \mathsf{S}(X) \otimes \mathsf{S}(X)$ 

$$\Delta \circ \mathrm{id}^{\vee m} = \sum_{p=0}^{m} \sum_{\sigma \in \mathrm{Sh}(p,m-p)} (\mathrm{id}^{\vee p} \otimes \mathrm{id}^{\vee (m-p)}) \circ \tau^{\sigma} \ , \ p,m \geq 0 \ ,$$

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 $\leadsto L_{\infty}$ -algebra as a coalgebra with coderivation and counit  $\varepsilon: S(X) \to K$ , where  $\varepsilon(1) = 1$  and  $\varepsilon(x) = 0$ ,  $x \in X$ .

## $L_{\infty} \rightsquigarrow \mathsf{Hopf} \ \mathsf{algebra}$

Graded symmetric tensor algebra S(X) has an algebra structure given by the graded symmetric tensor product  $\vee$  and a unit map  $\eta: K \to S(X)$ , where  $\eta(1) = 1$ .

The algebra and coalgebra structure on  $\mathsf{S}(X)$  make up a bialgebra, that admits a graded antipode map S

$$S(x_1 \vee \cdots \vee x_m) = (-1)^m (-1)^{\sum_{i=2}^m \sum_{j=1}^{i-1} |x_i| |x_j|} x_m \vee \cdots \vee x_1.$$

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the homotopy Lie algebra defined by the coalgebra structure on the graded symmetric tensor space S(X) extends to a cocommutative and coassociative Hopf algebra with compatible coderivation. Grewcoe, LJ, Kodzoman, Manolakos, '22

#### Non-commutative deformation

→ introduce non-(co)commutative deformation using Drinfel'd twist.

Using invertible twist element  $\mathcal{F}=:f^{\alpha}\otimes f_{\alpha}\in H\otimes H$ 

$$\begin{split} (\mathcal{F} \otimes 1)(\Delta \otimes id)\mathcal{F} &= (1 \otimes \mathcal{F})(id \otimes \Delta)\mathcal{F} \ , \\ (\epsilon \otimes id)\mathcal{F} &= 1 \otimes 1 = (id \otimes \epsilon)\mathcal{F} \ , \end{split}$$

we obtain  $(H^{\mathcal{F}}, \vee, \Delta^{\mathcal{F}}, S^{\mathcal{F}}, \epsilon)$ , where  $H^{\mathcal{F}}$  is the same as H as vector spaces and:

$$\Delta^{\mathcal{F}}(h) = \mathcal{F}\Delta(h)\mathcal{F}^{-1}, \ h \in H \ ,$$

and  $S^{\mathcal{F}} = S$  for Abelian twist.

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$$\leadsto$$
 twisted  $L_{\infty}$  or  $(L_{\infty}^{\mathcal{F}}, \vee, \Delta^{\mathcal{F}}, \mathcal{S}, \epsilon)$ 

#### Drinfel'd twist

In the spirit of deformation quantisation, while twisting Hopf algebra we simultaneously twist its modules. Taking Hopf algebra  $L_{\infty}$  as its own module  $(L_{\infty}^*, \vee_*, \Delta_*, S_*, \epsilon)$ :

$$\begin{aligned} x_1 \vee_{\star} x_2 &= \bar{f}^{\alpha}(x_1) \vee \bar{f}_{\alpha}(x_2) , \\ \Delta_{\star}(x) &= x \otimes 1 + \bar{R}^{\alpha} \otimes \bar{R}_{\alpha}(x) , \\ S_{\star}(x) &= -\bar{R}^{\alpha}(x) \bar{R}_{\alpha} . \end{aligned}$$

The  $\mathcal{R}$ -matrix  $\mathcal{R} \in S(X) \otimes S(X)$  is an invertible matrix induced by the twist

$$\mathcal{R} = f_{\alpha} \bar{f}^{\beta} \otimes f^{\alpha} \bar{f}_{\beta} =: R^{\alpha} \otimes R_{\alpha} , \mathcal{R}^{-1} = \bar{R}^{\alpha} \otimes \bar{R}_{\alpha} ,$$

The inverse  $\mathcal{R}$ -matrix controls noncommutativity of the  $\vee_{\star}$ -product and provides the representation of permutation group, e.g.,

$$\tau_{\mathcal{R}}^{\sigma}(x_1 \vee_{\star} x_2) = (-1)^{|x_1||x_2|} \bar{R}^{\alpha}(x_2) \vee_{\star} \bar{R}_{\alpha}(x_1) ,$$

## Braided $L_{\infty}$ -algebra

Extend the coproduct to whole tensor algebra:

$$\Delta_\star \circ \mathrm{id}^{\vee_\star m} = \sum_{\sigma \in \mathrm{Sh}(\rho, m-\rho)} (\mathrm{id}^{\vee_\star \rho} \otimes \mathrm{id}^{\vee_\star (m-\rho)}) \circ \tau_\mathcal{R}^\sigma \ , \ \rho, m \geq 0 \ .$$

The compatible coderivation  $D_\star = \sum_{i=0}^\infty b_i^\star$  is defined in terms of braided graded symmetric maps  $b_i^\star$ 

$$b_i^\star \circ \mathrm{id}^{\vee_\star j} = \sum_{\sigma \in \mathrm{Sh}(i,j-i)} \bigl( b_i^\star \vee_\star \mathrm{id}^{\vee_\star (j-i)} \bigr) \circ \tau_\mathcal{R}^\sigma \ , \ j \geq i \ ,$$

$$b_i^{\star}(x_1,\ldots,x_m,x_{m+1},\ldots,x_i) = (-1)^{|x_m||x_{m+1}|}b_i^{\star}(x_1,\ldots,\bar{R}^{\alpha}(x_{m+1}),\bar{R}_{\alpha}(x_m),\ldots,x_i) ,$$

and the condition  $D_{\star}^2=0$  reproduces the deformed homotopy relations.

 $\leadsto$  braided  $L_{\infty}$ -algebra obtained in Dimitrijević Ćirić et al '21.

$$L_{\infty}^{\star}$$
 vs.  $L_{\infty}^{\mathcal{F}}$ 

As Hopf algebras  $L_{\infty}^{\star}$  and  $L_{\infty}^{\mathcal{F}}$  are isomorphic Aschieri et al '05, Schenkel '12  $\exists$  map  $\varphi: L_{\infty}^{\star} \to L_{\infty}^{\mathcal{F}}$  such that

$$\varphi(x_1 \vee_{\star} x_2) = \varphi(x_1) \vee \varphi(x_2) ,$$
  

$$\Delta_{\star} = (\varphi^{-1} \otimes \varphi^{-1}) \circ \Delta^{\mathcal{F}} \circ \varphi ,$$
  

$$S_{\star} = \varphi^{-1} \circ S^{\mathcal{F}} \circ \varphi .$$

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$$S_{\star} = \varphi^{-1} \circ S^{\mathcal{F}} \circ \varphi .$$

On the other hand, we take  $L_\infty^\star$ -algebra as a module of  $L_\infty^\mathcal{F}$  with an  $L_\infty$ -action on an  $L_\infty$ -algebra given by an  $L_\infty$ -morphism Mehta, Zambon '12. Thus we obtain

$$D_{\star} = \varphi^{-1} D_{\mathcal{F}} \varphi .$$

## DFT algebroid

#### Double Field Theory

Hull, Zwiebach '09, Hohm, Hull, Zwiebach '10

A proposal for a field theory defined on double, 2d-dimensional configuration space with manifest T-duality <code>Duff '90, Tseytlin '90, Siegel '93.</code>

It uses doubled coordinates  $(x^A) = (x^a, \tilde{x}_a)$ , and fields (here only g, B) depend on both.

Global symmetry group G = O(d, d) with metric

$$\eta = (\eta_{AB}) = \begin{pmatrix} 0 & 1_d \\ 1_d & 0 \end{pmatrix} ,$$

used to raise and lower  $A = 1, \dots, 2d$  curved indices.

All objects in the theory belong to some representation of the O(d, d) duality group.

The fields in frame formalism, d-dimensional bein  $e^{m}_{a}$  and B collect into generalized bein

$$\mathcal{E}^{M}{}_{A} = \begin{pmatrix} e_{m}{}^{a} & e_{m}{}^{b}B_{ba} \\ & e_{a}^{m} \end{pmatrix}$$
 ,  $\mathcal{E}^{M}{}_{A} \in G$  ,

satisfying  $\eta_{AB}\mathcal{E}_I{}^A\mathcal{E}_J{}^B=\hat{\eta}_{IJ}$  for

$$\hat{\eta} = (\hat{\eta}_U) = \begin{pmatrix} 0 & 1_d \\ 1_d & 0 \end{pmatrix} ,$$

used to raise and lower I = 1, ..., 2d flat indices.

Local gauge symmetry combines standard diffeomorphisms and gauge trafos of B, generated by an O(d, d) vector  $\epsilon^A = \mathcal{E}_M{}^A \lambda^M$ .

The gauge algebra (of generalized Lie derivative) closes after imposing the strong constraint,

$$L_{\epsilon_1}L_{\epsilon_2}-L_{\epsilon_2}L_{\epsilon_1}=L_{\llbracket \epsilon_1,\epsilon_2\rrbracket}\;,$$

with the bracket operation, called the C-bracket, being

$$\llbracket \epsilon_1, \epsilon_2 \rrbracket^B = \epsilon_1^A \partial_A \epsilon_2^B - \frac{1}{2} \epsilon_1^A \partial^B \epsilon_{2A} - (\epsilon_1 \leftrightarrow \epsilon_2) \ .$$

Q: What are the properties of C-bracket?

## DFT algebroid

Chatzistavrakidis, L.J, Khoo, Szabo, '18

Let  $\mathcal M$  be a 2d-dimensional manifold. A DFT algebroid is a quadruple  $(L, \llbracket \cdot, \cdot 
rbracket, \langle \cdot, \cdot 
angle_L, \rho)$ , where L is vector bundle of rank 2d over  $\mathcal M$  equipped with

- a skew-symmetric bracket  $\llbracket \, \cdot \, , \, \cdot \, \rrbracket : \Gamma(L) \otimes \Gamma(L) \to \Gamma(L)$ ,
- a non-degenerate symmetric form  $\langle \, \cdot \, , \, \cdot \, \rangle_L : \Gamma(L) \otimes \Gamma(L) \to C^\infty(\mathcal{M})$ ,
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#### such that

- **2**  $[e_1, f e_2] = f [e_1, e_2] + \rho(e_1) f e_2 \langle e_1, e_2 \rangle_L \mathcal{D} f$

for all  $e_i \in \Gamma(L)$  and  $f, g \in C^{\infty}(\mathcal{M})$ , where  $\mathcal{D} : C^{\infty}(\mathcal{M}) \to \Gamma(L)$  is the derivative defined through  $\langle \mathcal{D}f, e \rangle_L = \frac{1}{2} \, \rho(e)f$ .

## DFT algebroid as curved $L_{\infty}$

Grewcoe, LJ '20

Maps:

$$\stackrel{\cdot}{b_0} = \eta \ , b_1(f) = \mathcal{D} f \ , b_1(e) = \rho(e) \ , b_2(\eta,f) = -\frac{1}{2} \eta^{-1}(df) \ , ...$$

Homotopy relations:

$$b_2(b_0, f) + b_1^2(f) = 0 \rightsquigarrow (\rho \circ \mathcal{D})f = \frac{1}{2}\eta^{-1}(df)$$

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 $L_{\infty}$  structure  $\leadsto$  cohomological vector  $Q=D^* \leadsto Q$ -manifold locally

Grewcoe, LJ '20

Evaluate  $b_i$  on basis of X  $\leadsto$  structure constants of  $L_{\infty}$ -algebra:

$$b_i(\tau_{\alpha_1},...,\tau_{\alpha_i})=C^{\beta}_{\alpha_1...\alpha_i}\tau_{\beta}$$

Use to define cohomological vector Q of degree 1

$$Q = \sum_{i=0}^{\infty} \frac{1}{i!} C_{\alpha_1 \dots \alpha_i}^{\beta} z^{\alpha_1} \cdots z^{\alpha_i} \frac{\partial}{\partial z^{\beta}}$$

with  $z^{\alpha_i}$  basis of  $\mathsf{X}^\star \leadsto Q = D^*$  . In DFT with  $\rho$  projection:

$$Q = \eta^{AB} \frac{\partial}{\partial s^{AB}} + \left( \delta^{A}_{I} e^{I} - \frac{1}{2} s^{AB} f_{B} \right) \frac{\partial}{\partial x^{A}} + \frac{1}{2} \hat{\eta}^{IJ} \delta^{A}_{I} f_{A} \frac{\partial}{\partial e^{J}},$$

Q-manifold locally as  $\mathbb{R}[-1] \oplus \mathbb{R}^{2d} \oplus \mathbb{R}^{2d}[1] \oplus \mathbb{R}^{2d}[2]$  with the coordinates  $\{s^{AB}, x^A, e^I, f_A\}$ .

$$\label{eq:Q2} \textbf{\textit{Q}}^2 = \textbf{\textit{0}} \leadsto \boldsymbol{\eta}^{AB} = \hat{\boldsymbol{\eta}}^{IJ} \boldsymbol{\delta}_I^A \boldsymbol{\delta}_J^B \ ,$$

#### Outlook

•  $Q = D^* \rightsquigarrow \mathsf{BRST}$  operator

Geometrically, a solution of classical master equation can be considered as a QP-manifold, i.e. a supermanifold equipped with an odd vector field Q obeying  $\{Q,Q\}=0$  and with Q-invariant odd symplectic structure. Cyclic  $L_{\infty}$ ! AKSZ '95

 In DFT algebroid no symplectic structure. Use graded contact structure to define an action?